General Dynamic Scene Reconstruction from Multiple View Video





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Motivation and Contributions

Limitations of existing multiple wide-baseline dynamic scene reconstruction technique:

1. They work in controlled environments;

2. Assumption of known background appearance and structure;

3. Fixed and calibrated cameras.

Contributions:

 An automatic method for initial coarse dynamic scene reconstruction without prior knowledge of background appearance or structure;
A robust approach for joint segmentation refinement and dense reconstruction of dynamic scenes from wide-baseline moving cameras.

Proposed general scene reconstrution



Framework for proposed general scene reconstruction



Joint segmentation and reconstruction refinement

1. Depth at each pixel p is assigned from a set of depth values $D = \{d_1, ..., d_{|D|-1}, U\}$. Each d_i is obtained by sampling the optical ray from the camera and U is an unknown depth value to handle occlusions and to refine object segmentation.

2. Energy minimization of the cost function is performed: $E(d) = \lambda_{data} E_{data}(d) + \lambda_{contrast} E_{contrast}(d) + \lambda_{smooth} E_{smooth}(d)$

- 3. Each dynamic object with the region $R_I + R_O$ is processed separately.
- 4. We divide our depth labels in two sets, one for the region R_I (D_I) and other for R_O (D_O) such that $|D_I| < |D_O|$

5. The equation consist of three terms: the data term is for the photo-consistency scores, the smoothness term is to avoid sudden peaks in depth and maintain the consistency and the contrast term is to identify the object boundaries.



- 1. The proposed approach allows unsupervised reconstruction without prior information on scene appearance or structure.
- 2. The segmentation and reconstruction accuracy are significantly improved over previous methods allows application to more general dynamic scenes.
- 3. Tests on challenging datasets demonstrate improvements in quality of reconstruction and segmentation compared to state-of-the-art methods.

References

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Acknowledgements

This research was supported by the European Commission, FP7 IMPART project (grant 316564).